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<input checked="" type="checkbox"/>	胡, J; (...) ; 高, HJ	自动控制杂志	一种用于具有缺失测量的时变复杂网络的递归状态估计的方差约束方法	2016	64		155-162	10.1016/j.automatica.2015.11.008	360

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Ogata, WI and Enyioha, C
2026 | IEEE ACCESS 14, pp.2045-2061
In teams of sensors or autonomous systems that cooperate to perform a task, communication can be a bottleneck for successful coordination. We propose a communication-efficient Quantized Distributed Extended Kalman Filter (QDEKF) for estimating the state of a weakly nonlinear system via a network of distributed sensors operating in a communicatior ... 显示更多

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Fang, PF; Li, WL; (...) ; Song, J
Dec 2025 | IEEE TRANSACTIONS ON AEROSPACE AND ELECTRONIC SYSTEMS 61(6), pp.17069-17083
This study addresses the problem of simultaneously estimating the system states and inferring the topology matrices in a class of Markov jump interconnected systems (MJISs), wherein the interactions among agents are characterized by the unknown topology matrices, and the system parameters evolve over time according to a finite-state Markov ch... 显示更多

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Zheng, ZQ; Song, HY and Fang, JL
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This study proposes a new theoretical framework focused on enhancing multi-sensor fusion estimation within cyber-physical systems, particularly in scenarios where sensor data may be disrupted by hybrid attacks, which involve both denial-of-service (DoS) and false data injection (FDI) attacks. The framework is built on the assumption that hybrid att... 显示更多

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8 **PID control and PI state estimation for complex networked systems: a survey** 10
 Zhao, D; Gao, C; (...); Ding, DR 被引频次
 Aug 18 2025 | INTERNATIONAL JOURNAL OF SYSTEMS SCIENCE 56(11), pp.2735-2750 126
 The integration of networked systems with control and state estimation presents a variety of challenges, a prominent one being the performance degradation of data communication due to network-enhanced complexities. Due to their multi-loop architectures, proportional-integral-derivative (PID) controllers and proportional-integral (PI) observ ... 显示更多

9 **Adaptive Sliding Mode Synchronous Control for Complex Networks With Amplify-and-Forward Relays** 1
 Yi, Y; Wei, Q; (...); Keiping, W 被引频次
 2025 | IEEE TRANSACTIONS ON AUTOMATION SCIENCE AND ENGINEERING 22, pp.16682-16691 52
 This paper aims to the remote synchronous control for complex networks with amplify-and-forward (AF) relays. Firstly, the AF relay dynamic with random noise is integrated into the control signal transmission. Secondly, the complex networks incorporating an AF relay is converted into the sliding control mode (SMC), which robustly addresses ... 显示更多

10 **Event-Triggered Distributed Resilient State Estimator for Nonlinear Cyber-Physical Systems Under Hybrid Cyberattacks** 1
 Wu, ZW and Zhang, LW 被引频次
 Mar 2025 | INTERNATIONAL JOURNAL OF ADAPTIVE CONTROL AND SIGNAL PROCESSING 39(3), pp.529-543 49
 This article investigates the problem of event-triggered distributed resilient state estimator (ET-DRSE) for nonlinear cyber-physical systems (NCPs) under hybrid cyberattacks. A stochastic model for hybrid cyberattacks is constructed by considering both false data injection (FDI) and Denial-of-Service (DoS) attacks. By proposing an event triggered n ... 显示更多

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Chen, DY; Yao, MY; (...); Liu, JT
Sep 2025 (在线发表) | INTERNATIONAL JOURNAL OF CONTROL

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This paper studies the sequential fusion estimation problem for state-saturated nonlinear complex networks under unknown but bounded (UBB) noises. The UBB noises are contained by a set of zonotopes. The centre difference method based on the second-order Stirling interpolation formula is used to approximate the nonlinear function, and the product o ... 显示更多

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Liu, Z and Bao, HB
Feb 2026 | SIGNAL PROCESSING 239

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This paper investigates, for the first time, the state estimation (SE) problem in complex networks with data distortion and delay under various noise conditions. To address data distortion and delay effects caused by dynamic bias, observation fading, and random interference, this paper proposes two recursive state estimation algorithms based on Gaussi... 显示更多

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Yu, DD; Xia, YQ; (...); Zhang, Y

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Ogata, W and Enyioha, C
2026 | IEEE ACCESS 14, pp.2045-2061

In teams of sensors or autonomous systems that cooperate to perform a task, communication can be a bottleneck for successful coordination. We propose a communication-efficient Quantized Distributed Extended Kalman Filter (QDEKF) for estimating the state of a weakly nonlinear system via a network of distributed sensors operating in a communica...

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240(3), pp.536-551

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Chen, DY; Yao, MY; ...; Liu, JT

Sep 2025 (在线发表) | INTERNATIONAL JOURNAL OF CONTROL

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11、按以上格式要求, 打印检索结果 (请将被引用文章标题汇总记录在 WORD 文档中, 便于工作人员核对), 到南区图书馆 1006 室由工作人员核对无误后盖上检索专用章。