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注意事项：开具 SCI 他引证明前，请先自行查询 SCI 库基本检索，确保被引用的文章已被 SCI 库收录，然后再进行 SCI 他引证明打印，否则后果自负。如需证明文章被 SCI 收录，请另外开具 SCI 收录证明。

打印 SCI 他引证明操作流程如下：

1、进入图书馆网站主页-“资源”-“引进数据库”-“外文”

选择进入“SCI 美国科学引文索引”，点击访问网址进入 SCI 主页。

访问网址：http://www.webofknowledge.com

进入SCI平台前，仔细阅读SCI打印格式说明：

1、进入SCI后，将右上角语言切换成中文

2、进入 SCI 数据库，选择数据库“Web of Science 核心合集”，引文索引“SCI-EXPANED2004-至今”。

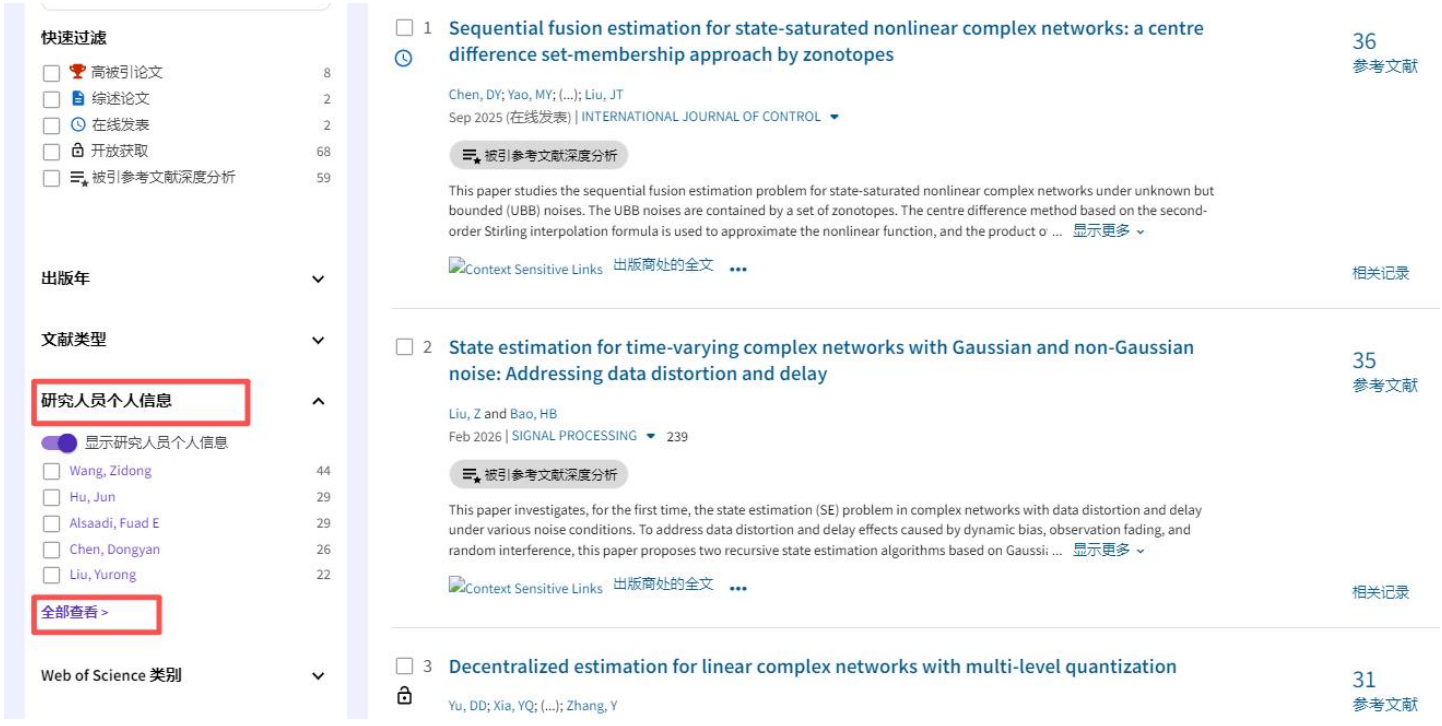
3、点击“被引参考文献”，选择“被引标题”，填入检索内容（请将题目输全），点击“检索”。

4、勾选所需文献，点击“查看结果”。

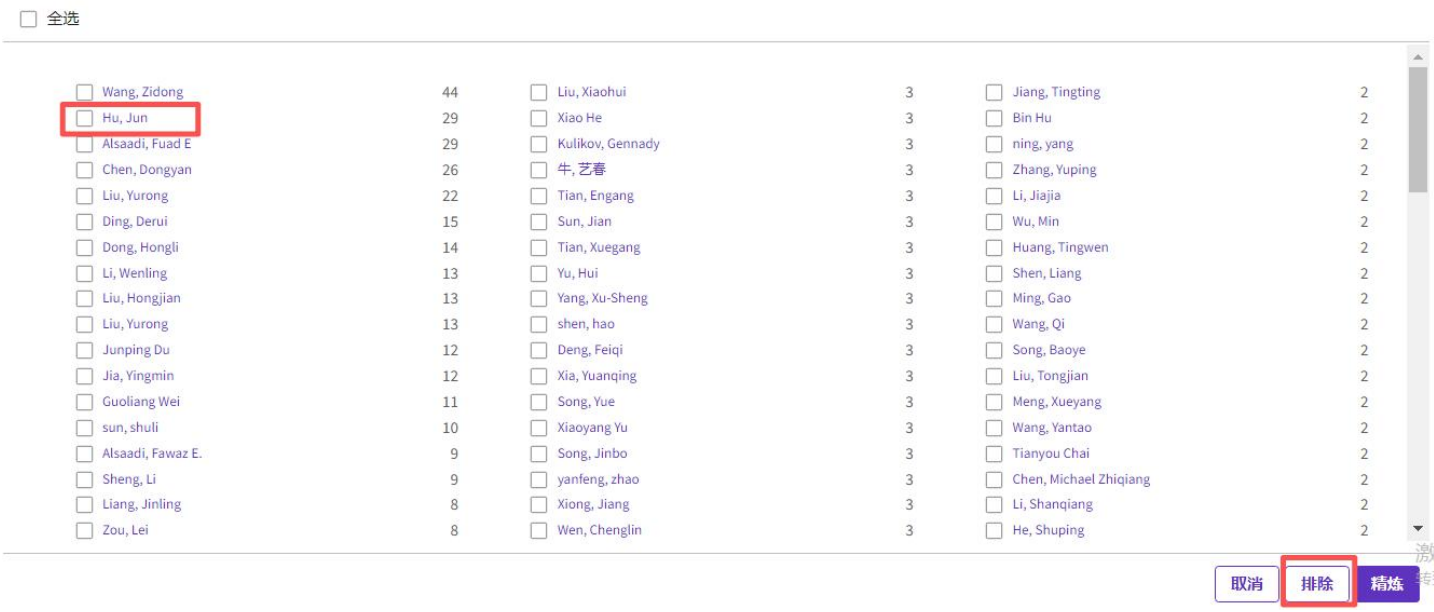
5、核对检索结果页面信息，打开页面左侧下方“Web of Science 索引”链接，显示索引内容，核对是否是“SCI-Expanded”。

6、如没有作者需要排除，则联机打印该检索结果页面即可（在页面上点击右键，选择“打印”，直接连接打印机打印此页，打印时需勾选页眉页脚,放缩比例设置成 60%，根据需要打印首页或全部页）。注意：必须联机打印，不可以保存 PDF 后再打印，打印时注意勾选页眉与页脚，即需显示联机打印时间和打印地址，页面上的“Web of Science 索引”链接也需要打开，显示索引内容。

7、如果有作者需要排除，请继续下列步骤，左侧“研究人员个人信息” 点击“全部查看”



8、勾选要排除的作者姓名，点“排除”



9、得到他引结果页面，核对排除作者及检索结果是否正确，打开“Web of Science 索引”链接，显示索引内容，核对是否是“SCI-Expanded”，点击右键“打印”该页面。

10、SCI 他引证明打印样例，如下图，根据需要打印首页或全部页。

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A variance-constrained approach to recursive state estimation for time-varying complex (被引标题)

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精炼依据: NOT 研究人员个人信息: Hu, Jun ✕ 全部清除

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1 **Sequential fusion estimation for state-saturated nonlinear complex networks: a centre difference set-membership approach by zonotopes**

Chen, DY; Yao, MY; (...); Liu, JT

Sep 2025 (在线发表) | INTERNATIONAL JOURNAL OF CONTROL

被引参考文献深度分析

This paper studies the sequential fusion estimation problem for state-saturated nonlinear complex networks under unknown but bounded (UBB) noises. The UBB noises are contained by a set of zonotopes. The centre difference method based on the second-order Stirling interpolation formula is used to approximate the nonlinear function, and the product o ... 显示更多

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2 **State estimation for time-varying complex networks with Gaussian and non-Gaussian noise: Addressing data distortion and delay**

Liu, Z and Bao, HB

Feb 2026 | SIGNAL PROCESSING 249

被引参考文献深度分析

This paper investigates, for the first time, the state estimation (SE) problem in complex networks with data distortion and delay under various noise conditions. To address data distortion and delay effects caused by dynamic bias, observation fading, and random interference, this paper proposes two recursive state estimation algorithms based on Gaussi ... 显示更多

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3 **Decentralized estimation for linear complex networks with multi-level quantization**

Yu, DD; Xia, YQ; (...); Zhang, Y

Sep 2025 | AUTOMATICA 179

This paper addresses the decentralized state estimation problem for a class of discrete-time linear complex networks under communication constraints. Due to the limited communication bandwidth and radiated power, a multi-level quantization (MLQ) scheme is utilized to compress the measurement innovations transmitted over the sensor-to-estimat ... 显示更多

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- Wang, Zidong 37
- Alsaadi, Fuad E 25
- Liu, Yurong 19
- Ding, Derui 15
- Li, Wenling 13

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基金资助机构

会议名称

团体作者

4 **Fractional Kalman filters**

Yang, XS; Zhang, WA and Yu, L

Aug 2025 | AUTOMATICA 178

The nonlinear Kalman filters usually suffer from degradation when the measurements appear in the tail of prior distribution. This article presents a new nonlinear filter named the fractional Kalman filter (FKF) for high robustness against linearization errors of both the time and the measurement updates. Based on the Bayesian theory and Gaussian assumptio ... 显示更多

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5 **PID control and PI state estimation for complex networked systems: a survey**

Zhao, D; Gao, C; (...); Ding, DR

Aug 18 2025 | INTERNATIONAL JOURNAL OF SYSTEMS SCIENCE 56(11), pp.2735-2750

The integration of networked systems with control and state estimation presents a variety of challenges, a prominent one being the performance degradation of data communication due to network-enhanced complexities. Due to their multi-loop architectures, proportional-integral-derivative (PID) controllers and proportional-integral (PI) observ ... 显示更多

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6 **Adaptive Sliding Mode Synchronous Control for Complex Networks With Amplify-and-Forward Relays**

Yi, Y; Wei, Q; (...); Keping, W

2025 | IEEE TRANSACTIONS ON AUTOMATION SCIENCE AND ENGINEERING 22, pp.16682-16691

This paper aims to the remote synchronous control for complex networks with amplify-and-forward (AF) relays. Firstly, the AF relay dynamic with random noise is integrated into the control signal transmission. Secondly, the complex networks incorporating an AF relay is converted into the sliding control mode (SMC), which robustly addresses ... 显示更多

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7 **Event-Triggered Distributed Resilient State Estimator for Nonlinear Cyber-Physical Systems Under Hybrid Cyberattacks**

Wu, ZW and Zhang, LW

Mar 2025 | INTERNATIONAL JOURNAL OF ADAPTIVE CONTROL AND SIGNAL PROCESSING 39(3), pp.529-543

被引参考文献深度分析

This article investigates the problem of event-triggered distributed resilient state estimator (ET-DRSE) for nonlinear cyber-physical systems (NCPSs) under hybrid cyberattacks. A stochastic model for hybrid cyberattacks is constructed by considering both false data injection (FDI) and Denial-of-Service (DoS) attacks. By proposing an event-triggered m ... 显示更多

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8 **High-degree cubature particle filter for nonlinear system with missing measurements**

11、按以上格式要求，打印检索结果（请将被引用文章标题汇总记录在 WORD 文档中，便于工作人员核对），到南区图书馆 1006 室由工作人员核对无误后盖上检索专用章。